IN THE CLAIMS:

Please amend the claims to read as indicated herein.

- 1. (Cancelled)
- 2. (Currently amended) The contactless level transmitter of claim 3, wherein <u>the</u> at least <u>theone</u> segment of the annular magnet is adapted to be injected into a fuel-resisting plastic material of the lever.
- 3. (Currently amended) A level transmitter for liquid containers, particular fuel store tanks, comprising:

a housing in which <u>is arranged</u> a contactless sensor <u>is arranged which is</u> connected <u>withto</u> an evaluating unit and operatively connected <u>withto</u> a magnet that moves relative to the sensor upon movement of a float arranged at a first end of a lever, so that the change of the magnetic field acting upon the sensor is transformed into an electric signal so that an output signal corresponding to the level of the liquid in the container is obtainable by the evaluating means.

wherein saidthe magnet is configured at least as aat least one segment of an annular magnet that is arranged at a second end of saidthe lever and integrated therein, and

wherein the lever arm-is rotatably connected with the housing and supported thereat, and

wherein the sensor is located on a radial axis of the at least one segment of the annular magnet.

4. (Previously presented) The contactless level transmitter of claim 3, wherein

the sensor is freely programmable.

- 5. (Currently amended) The contactless level transmitter of claim 3, wherein the sensor is arranged on a printed circuit board together with suppressor modules, saidand wherein the printed circuit board has a fuel-resisting plastic material injected around and is integrated into the housing.
- 6. (Previously presented) The contactless level transmitter of claim 3, wherein the printed circuit board having the plastic material injected around is adapted to be mounted to the housing via a snap connection and the sensor is adapted to be led through an opening in the housing at the same time.
- 7. (Currently amended) The contactless level transmitter of claim 3, wherein the lever arm-is rotatably connected with the housing and supported thereat by means of either a clipping or locking engagement.
- 8. (New) The contactless level transmitter of claim 3, wherein the sensor is located between an axis of rotation of the lever and the at least one segment of the annular magnet.